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Numerical Simulation as a Modeling and Teaching Tool of Optical Devices and Systems

T.I. Yuk, S.F. Yu, P. Shum, and J.C. Palais*

Department of Electrical & Electronic Engineering, University of Hong Kong, Pokfulam, Hong Kong

Email: tiyuk@eee.hku.hk

* Department of Electrical Engineering, Arizona State University, Tempe, AZ.

ABSTRACT

This paper describes the development of numerical simulation models of an Er-doped waveguide laser and a mode-locked fiber soliton laser. The Er-doped waveguide laser model is a simple and straight-forward but powerful dynamic model using time domain algorithm. It is based on i) time dependent rate equations of a quasi-two-level-system for the population densities and ii) time-dependent traveling wave equations for the pump and signal power which are solved simultaneously in time-domain. The dynamic responses of population densities, pump and signal power are investigated. The model is used to study more sophisticated structure with cross-coupling from optical feedback of an etched grating. Another simulation model is developed to investigate the generation of sub-picosecond solitons in an active mode-locked fiber ring laser which consists of a polarization preserving Er-doped single mode fiber, an amplitude modulator and a phase modulator and has taken into account of dispersive spreading, self-phase modulation, finite amplification bandwidth, pump depletion, and Raman self-frequency shift. A newly developed numerical technique, Fourier Series Analysis Technique, is used to solve the non-linear Schrodinger equation of soliton propagation. Time trace of the soliton pulse propagation and its spectrum can be obtained under a wide range of operation conditions.

Keywords : simulation models, waveguide laser, fiber laser, solitons

2. INTRODUCTION

Wide spread research and development efforts are being spent in the field of opto-electronics. Numerous passive and active optical devices are designed and developed. Analytic and numerical modeling are the tools for designing and optimizing these devices and systems. For more advanced devices and systems, numerical simulation is often a better tool that can take into account more complex structures and configurations. Effects of various device and system parameters can be systematically studied in greater detail and compared with experimental data. In this paper, we describe numerical simulation models of an Er-doped waveguide laser and a mode-locked fiber soliton laser. The simulation models have been assigned and developed as student design projects. Understanding of these laser devices are greatly enhanced through the development of the simulation models.

Several numerical models have been recently developed to analyze the relaxation oscillation behavior of Er-doped Ti:LiNbO_3 waveguide laser [1,2]. In this paper we present a more straight-forward time-domain algorithm to calculate the dynamic response based on directly solving the time-dependent wave equations and the time-dependent quasi-two-level-laser rate equations. The model take into consideration of the longitudinal distribution of spontaneous emission noise. The transient responses of population densities, pump and signal power are investigated for Er^{3+} -doped Ti:LiNbO_3 waveguide lasers. To demonstrate the sophistication of this time-domain model, the influence of cross-coupled effect of the traveling waves due to the optical feedback of an etched grating is also studied. Dynamic response of the waveguide laser with and without grating are compared.

A second numerical simulation model is developed to investigate the generation of sub-picosecond solitons in active mode-locked fiber ring laser in both time and frequency domains. The laser model consists of a polarization preserving Er-doped single mode fiber, an amplitude modulator and a phase modulator. A relatively straight forward method is used to model the fiber laser using Fourier Series Analysis Technique. The advantages of using FSAT rather than the conventional split-step Fourier Method include better computation efficiency, less number of sampling points, and can handle higher order nonlinear terms without resort to other numerical methods. The model has taken into account of dispersive spreading, self-phase modulation, finite amplification bandwidth, pump depletion, and Raman self-

frequency shift. Time trace of the soliton pulse propagation and its spectrum can be obtained under a wide range of operation conditions.

3. MODELING OF Er³⁺-DOPED WAVEGUIDE LASER

3.1 Theoretical model

The schematic of optical pumped waveguide laser is shown in figure 1. The Er³⁺ ion is assumed to be uniformly distributed and have a concentration N_t . A grating is etched along the z direction to provide optical feedback. In our model, light of orthogonal (σ -) polarization (to the optical axis) is only considered in our analysis.

The interaction of the pump/signal photons with the Er³⁺ ions can be described by the rate equations of the populations N_2 and N_1 for the upper and lower levels expressed below [1], [2]:

$$\frac{dN_2}{dt} = (R_{12} + W_{12})N_1 - (A_{21} + R_{21} + W_{21})N_2 \quad (1)$$

$$N_1 = N_t - N_2 \quad (2)$$

where R_{12} (W_{12}) and R_{21} (W_{21}) are the pump (signal) absorption and emission rates respectively, $A_{21} = 1/\tau$ is the spontaneous rate of transition from the excited state to the ground state.

The evolution of the forward and backward propagating pump(signal) fields $p^+(s^+)$ and $p^-(s^-)$ is based on the time dependent travelling wave equation [3], [4]:

$$\begin{aligned} \left(\pm \frac{\partial}{\partial z} + \frac{1}{c_n} \frac{\partial}{\partial t} \right) p^\pm &= \frac{1}{2} \left(-\bar{\alpha}_p + \sigma_p^{21} N_2 - \sigma_p^{12} N_1 \right) p^\pm + i\kappa p^\mp + \tilde{\chi}_p \\ \left(\pm \frac{\partial}{\partial z} + \frac{1}{c_n} \frac{\partial}{\partial t} \right) s^\pm &= \frac{1}{2} \left(-\bar{\alpha}_s + \sigma_s^{21} N_2 - \sigma_s^{12} N_1 \right) s^\pm + i\kappa s^\mp + \tilde{\chi}_s \end{aligned} \quad (3)$$

where σ^{12} and σ^{21} is the absorption and emission cross-section, respectively. c_n is the group velocity, κ is the coupling coefficient of the propagation fields, $\bar{\alpha}_p$ and $\bar{\alpha}_s$ is the absorption and scattering loss of the pump and signal fields. The spontaneous emission coupled to the pump and signal is described by the terms $\tilde{\chi}_p$ and $\tilde{\chi}_s$, respectively.

In our time domain model, the waveguide laser is divided into a number of equal small sections M , as shown in Figure 2, each with length $\Delta z = L/M$, where L is the total length of the waveguide. In each section, the material and structure parameters are assumed to be constant, but they are allowed to change from section to section. By knowing the field value at time t and location z , the field for forward (reverse) waves at the next time $t + \Delta t$, where $\Delta t = \Delta z/c_n$, can be determined at position $z + \Delta z$ ($z - \Delta z$) from the equations to be derived below.

The coupled equations in (3) can be solved in time domain by a first-order difference approximation to the partial differential :

$$\frac{\partial F^+(t, z)}{\partial t} = \frac{F^+(t + \Delta t, z) - F^+(t, z)}{\Delta t} \quad (4a)$$

$$\frac{\partial F^+(t, z)}{\partial z} = \frac{F^+(t, z + \Delta z) - F^+(t, z)}{\Delta z} \quad (4b)$$

$$\frac{\partial F^-(t, z)}{\partial t} = \frac{F^-(t + \Delta t, z) - F^-(t, z)}{\Delta t} \quad (4c)$$

$$\frac{\partial F^-(t, z)}{\partial z} = \frac{F^-(t, z) - F^-(t, z - \Delta z)}{\Delta z} \quad (4d)$$

where $F=p, s$. The evolution of the field F at position z and time t to the adjacent section $z+\Delta z$ at time $t+\Delta t$ can be approximated as:

$$\begin{aligned} F(t+\Delta t, z+\Delta z) - F(t, z) &= F(t+\Delta t, z+\Delta z) - F(t, z+\Delta z) + F(t, z+\Delta z) - F(t, z) \\ &= \frac{\partial^2 F}{\partial t \partial z} \Delta t \Delta z + \frac{\partial F}{\partial t} \Big|_z \Delta t + \frac{\partial F}{\partial z} \Big|_t \Delta z \end{aligned} \quad (5)$$

If we choose the relation between the time and spatial steps as $\Delta z = c_n \Delta t$ and neglect the second derivative $\partial^2 F(t, z)/\partial t \partial z$, we can obtain the traveling wave formula as follows:

$$\begin{aligned} p^\pm(t+\Delta t, z \pm \Delta z) - p^\pm(t, z) &= \Delta z \left[\frac{1}{2} (-\bar{\alpha}_p + \sigma_p^{21} N_2 - \sigma_p^{12} N_1) p^\pm(t, z) + i\kappa p^\mp(t, z) + \tilde{\chi}_p(z) \right] \\ s^\pm(t+\Delta t, z \pm \Delta z) - s^\pm(t, z) &= \Delta z \left[\frac{1}{2} (-\bar{\alpha}_s + \sigma_s^{21} N_2 - \sigma_s^{12} N_1) s^\pm(t, z) + i\kappa s^\mp(t, z) + \tilde{\chi}_s(z) \right] \end{aligned} \quad (6)$$

If the number of sections of the laser waveguide M is sufficiently large, the following approximation can be used :

$$\frac{dN}{dt} = \frac{\Delta N}{\Delta t} \quad (7)$$

The time dependent rate equation given in (1) can thus be approximated as :

$$\Delta N_2 = ((R_{12} + W_{12})N_1 - (A_{21} + R_{21} + W_{21})N_2)\Delta t \quad (8)$$

where ΔN_2 is the change of population in the time interval Δt . The dynamic behavior of Er-doped waveguide laser can than be solved by using (6) & (8) in a self-consistent manner. In addition, the implementation of (6) & (8) is straight forward. The other advantages of this model are the non-linearity such as non-uniform distribution of signal power, pump power as well as Er^{3+} doped ion can also be taken into consideration.

3.2 Simulation results

Figure 3 compares the transient behavior of the waveguide lasers (a) without and (b) with longitudinal grating under a step response of pumped power. As we can see, the grating structure enhances relaxation oscillation frequency. This is because the photon lifetime is reduced significantly by the longitudinal optical feedback. In addition, mode beating is not observed at steady state in Figure 3b due to the frequency selective properties of longitudinal grating and single mode operation is maintained at steady state. One fundamental difference between our model and the models given in references [1,2] is that phase relation of the propagation waves is also taken into account in our model such that mode beating phenomena due to the competition of longitudinal modes is observed in our model. In our time domain model, many interesting parameters can be displayed as a function of time as shown in Figure 4.

4. MODELING OF MODE-LOCKED FIBER LASER

4.1 Theoretical model

The laser structure with a ring configuration used in our analysis is shown in Figure 5. It consists of a single mode polarization-preserving Er^{3+} -doped fiber to provide optical gain for the soliton pulses, an optical isolator to allow unidirectional generation, an amplitude modulator to start the mode-locking regime and a phase modulator to suppress

Raman self-frequency shift. If the soliton pulses generated from the mode-locked laser have pulse width not less than 100fs, the propagation of soliton pulses can be described by a simplified nonlinear equation [5]:

$$\frac{\partial u}{\partial z} = j \frac{1}{2} \frac{\partial^2 u}{\partial T^2} + j|u|^2 u + \frac{1}{2} G u + \frac{1}{2} \gamma_a G \frac{\partial u}{\partial T} - j \gamma_R u \frac{\partial |u|^2}{\partial T} \quad (9)$$

where u is the normalized amplitude, T is the normalized time and z is the normalized distance. $\gamma_a = T_2^i / \tau_o$, $T_2^i = 1 / (\pi \Delta \nu_a)$, $\Delta \nu_a$ is the amplification line bandwidth, $\gamma_R = 2\beta \mu \delta$, $\mu = (T_o \Omega_R)^{-1}$, $\delta = (T_2^R \Omega_R)^{-1}$, Ω_R is the Raman resonant frequency and $T_2^R (= 1 / (\pi \Delta \nu_R))$ is the characteristic time. In (1), the first term in the right hand side describes the pulse dispersion spreading, the second term describes the Kerr effect, the third and forth terms represent the finite gain bandwidth and pump depletion of Er^{3+} fiber, respectively. The last term describes the Raman self-frequency shift of the laser. The amplification parameter G is defined as

$$G = \frac{G_o}{(1 + \sigma W_l / W_p)} \quad (10)$$

where $W_l = \int_{-T/2}^{T/2} |u|^2 dt$ is the laser pulse energy, the coefficient σ is proportional to the ratio of pumped and laser transition cross sections, and W_p is the pump energy per period.

Equation (9) can be solved by FSAT to analyze the formation of soliton pulses [6]. First, by expressing $u(z, T)$ from (9) in terms of Fourier series as shown below:

$$\sum_{n=-N}^N \frac{\partial \hat{u}_n(z)}{\partial z} \exp(jn\epsilon T) = -\frac{1}{2} j \sum_{n=-N}^N n^2 \epsilon^2 \hat{u}_n(z) \exp(jn\epsilon T) + j \sum_{n=-N}^N \Psi_n(z) \exp(jn\epsilon T) - j \gamma_R \sum_{n=-N}^N \Phi_n(z) \exp(jn\epsilon T) \quad (11)$$

where

$$\sum_{n=-N}^N \Psi_n(z) \exp(jn\epsilon T) = \left| \sum_{n=-N}^N \hat{u}_n(z) \exp(jn\epsilon T) \right|^2 \cdot \sum_{n=-N}^N \hat{u}_n(z) \exp(jn\epsilon T), \quad (12a)$$

$$\sum_{n=-N}^N \Phi_n(z) \exp(jn\epsilon T) = \sum_{n=-N}^N \hat{u}_n(z) \exp(jn\epsilon T) \cdot \frac{\partial}{\partial T} \left| \sum_{n=-N}^N \hat{u}_n(z) \exp(jn\epsilon T) \right|^2. \quad (12b)$$

The parameters $\hat{u}_n(z)$ and ϵ are the Fourier amplitude coefficient and the fundamental frequency, respectively. Then, using the orthogonal property of the exponential coefficients, the required $2N+1$ first order partial differential equations can be obtained and are given as follows:

$$\frac{\partial \hat{u}_n(z)}{\partial z} = \underbrace{[-j\sigma(n) + \frac{1}{2} G] \hat{u}_n(z)}_{\text{linear term}} + \underbrace{j \sum_{\forall \mu-\nu+\lambda=n} \hat{u}_\mu(z) \hat{u}_\nu^*(z) \hat{u}_\lambda(z) + \gamma_R \epsilon \sum_{\forall p+q=n} q \hat{u}_p(z) \Theta_q(z)}_{\text{nonlinear term}} \quad (13)$$

where $n, \mu, \nu, \lambda, p, q, k, L$ and m are integers of values between $-N$ and N . $\sigma(n) = \frac{1}{2} n^2 \epsilon^2 - \frac{1}{2} \gamma_a G n \epsilon$ and

$\Theta_q(z) = \sum_{\forall a-b=q} \hat{u}_a(z) \hat{u}_b^*(z)$. A time-domain window function term can be introduced into the first order partial differential

equations to improve the computational efficiency [7]. The propagation of soliton along the Er^{3+} doped fiber can be calculated by solving (13) through the Runge-Kutta Method. At each propagation distance, the soliton propagation results of (13) can be transformed to time domain by inverse FFT.

The transmission function of both amplitude and phase modulators are modeled as shown below:

$$K_a = t_a \exp[-d_a \sin^2(\Omega_a T + \phi_a)] \quad (14a)$$

$$K_p = \exp[jd_p \cos(\Omega_p T + \phi_p)] \quad (14b)$$

where d_a (d_p), Ω_a (Ω_p) and ϕ_a (ϕ_p) are the depth, frequency and phase of the amplitude (phase) modulation, respectively. The information of soliton pulse after the gain section in time domain is used as the initial boundary conditions for the amplitude and phase modulators. The output of the modulators will then be transformed back into frequency domain as the initial conditions for the Er^{3+} doped fiber. The above process will repeat until the predefined propagation distance (i.e. number of pass) is reached.

4.2 Simulation results

Figures 6 and 7 shows the evolution of soliton pulses in time and frequency domains generated from pure active mode-locking and with self phase modulation respectively. In the calculation, the initial pulse shape is assumed as $u(0,T)=\text{sech}(T)$. The other parameters used in the calculation are the same as [5] except $K=5$ and $T_0=8$.

Figure 8 shows the variation of pulse with gain parameter G_0 . It is observed that the pulse width is decreased exponentially with G_0 and the profile is close to that given in [5]. Therefore, we have shown that the simulation results are well agreed with [5] and the proposed FSAT method in modeling of active model-lock fiber laser is reliable. The influence of energy loss coefficient, pump energy and active fiber length on pulse power is shown in Figure 9.

5. CONCLUSIONS

The paper has presented two numerical simulation models to illustrate the usefulness of simulation as a modeling and teaching tool to enhance the understanding of optical devices and systems. Development of the simulation programs can serve as student research projects. The simulation programs developed can serve as teaching tools or as project assignments to illustrate the performances of the waveguide laser and fiber laser as a function of device parameters.

6. REFERENCES

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Figure 1. Schematic of Er^{3+} -doped waveguide laser

Figure 2. A waveguide model showing the time-domain algorithm principle.

Figure 3. Calculated relaxation oscillations of the Er-doped waveguide laser (a) without grating, (b) with grating under a step injection optical power.

Figure 4. Time evolution of (a) the pump power, (b) expanded view of the inversion population, signal and pump power.

Figure 5. The schematic of an active mode-lock Er^{3+} doped fiber laser in ring configuration.

Figure 6. The propagation of soliton pulses in an pure active mode-locked fiber laser (without self-phase modulation).

Figure 7. Evolution of laser radiation in the case of soliton shaping.

Figure 8. Plot of steady state pulse width against gain parameter G_0 .

Figure 9. Plot of steady state peak power against (a) energy loss coefficient of amplitude modulator, (b) pump energy, and (c) length of active Er-doped fiber.