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**Alexander V. Bernstein
Adrian Olaru
Jianhong Zhou**
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Contents

- v *Authors*
- vii *Conference Committee*
- ix *Introduction*

SESSION 1 COMPUTER VISION AND PHOTOGRAPHY

- 10253 02 **A calibration technique for the stereo camera system with the laser illumination** [10253-7]
- 10253 03 **Estimation of velocities via optical flow** [10253-11]
- 10253 04 **Fighting detection using interaction energy force** [10253-16]
- 10253 05 **Verification of applicability two multiplicative closed spectral models for multiple reflection effect description** [10253-14]
- 10253 06 **Trainable Siamese keypoint descriptors for real-time applications** [10253-9]

SESSION 2 IMAGE ANALYSIS AND PROCESSING

- 10253 07 **Noise estimation for color visualization of multispectral images** [10253-10]
- 10253 08 **Blind radial distortion compensation from video using fast Hough transform** [10253-1]
- 10253 09 **Portable digital device UHDTV panoramic image formation** [10253-21]
- 10253 0A **Image fractal coding algorithm based on complex exponent moments and minimum variance** [10253-22]
- 10253 0B **CT image quality assessment based on morphometric analysis of artifacts** [10253-6]
- 10253 0C **Bayes filter modification for drivability map estimation with observations from stereo vision** [10253-17]

SESSION 3 ROBOT DESIGN AND CONTROL

- 10253 0D **Stereo-based visual localization without triangulation for unmanned robotics platform** [10253-15]
- 10253 0E **Position control of an industrial robot using fractional order controller** [10253-18]

10253 0F **Evaluation of approaches combining 2D and 3D data for object recognition developed for the mobile robot Lisa** [10253-5]

10253 0G **Manifold learning in machine vision and robotics** [10253-24]

SESSION 4 MECHANICAL CONTROL AND AUTOMATION

10253 0H **H_∞ control strategy for a class of switched Hamiltonian systems** [10253-13]

10253 0I **Friend or foe: exploiting sensor failures for transparent object localization and classification** [10253-4]

10253 0J **A rail wear measurement method based on structured light scanning** [10253-19]

10253 0K **The stress analysis and tests in the bottom of the hinge beam block of cubic press** [10253-8]

10253 0L **Statistical analysis of the characteristics of high degree polynomial solving methods used in the five-point algorithm** [10253-12]

10253 0M **Decentralized control algorithms of a group of vehicles in 2D space** [10253-20]

Authors

Numbers in the index correspond to the last two digits of the six-digit citation identifier (CID) article numbering system used in Proceedings of SPIE. The first four digits reflect the volume number. Base 36 numbering is employed for the last two digits and indicates the order of articles within the volume. Numbers start with 00, 01, 02, 03, 04, 05, 06, 07, 08, 09, 0A, 0B...0Z, followed by 10-1Z, 20-2Z, etc.

Abrudean, Mihail, 0E
Barthen, Andreas, 0I
Bernstein, Alexander V., 0G
Buzmakov, Alexey, 0B
Chen, Peng, 0J
Chukalina, Marina, 0B
Clitan, Andrei, 0E
Clitan, Iulia, 0E
Ershov, Egor, 05, 0D, 0L
Fedorenko, Fedor A., 06
Fedorenko, R. V., 0M
Gladilin, Sergey, 05, 07, 08, 0D
Gladkov, Andrey, 0B
Gurenko, B. V., 0M
Gusamutdinova, Nuriya, 05
Ingacheva, Anastasia, 0B
Ivan, Yakimchuk, 0B
Ivanova, Alena A., 06
Konovalenko, Ivan A., 06, 07
Konstantinov, I. S., 09
Kunina, I. A., 08
Lauer, Martin, 0J
Lazarev, S. A., 09
Limonova, Elena E., 06
Ma, Liang, 0K
Ma, Xianglong, 0K
Marohn, Philipp, 0I
Maslakov, Y. N., 09
Maximov, Y., 07
Medvedev, M. Yu., 0M
Miller, A., 03
Miller, B., 03
Miron, Radu, 0E
Muresan, Vlad, 0E
Nikiforov, Michael B., 02
Nikolaev, Dmitry, 05, 08, 0B, 0D
Ovchinkin, Anton, 0L
Panchenko, Aleksei, 0C
Paulus, Dietrich, 0F, 0I
Ping, Ziliang, 0A
Polster, Florian, 0F
Popov, A., 03
Prun, Viktor, 0C
Pshikhopov, V. Kh., 0M
Rubcov, K. A., 09
Sablina, Victoria A., 02
Seib, Viktor, 0F, 0I
Sidorchuk, D., 07
Stepanyan, K., 03
Suvonvorn, Nikom, 04
Terekhin, A. P., 08
Tu, Pu, 0H
Turchenkov, Dmitri, 0C
Volkov, Alexey, 0D
Wang, Jindong, 0J
Wang, Peijun, 0J
Wateosot, Chonthisa, 04
Yang, Feixia, 0A
Yuan, Yuan, 0K
Zhang, Yinghong, 0K
Zhang, Zhisen, 0H
Zhao, Quanjun, 0H
Zhou, Suhua, 0A
Zhu, Huawei, 0H

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Introduction

The 2016 International Conference on Robotics and Machine Vision (ICRMV) provided a forum for the most up-to-date and authoritative knowledge from both the industrial and academic worlds, sharing the newest research fruits and experiences in this exciting field. This inaugural ICRMV was held in Moscow, Russia, 14-16 September 2016.

The scientific program for the event was filled with presentations delivered by researchers and scholars from the international community, including keynote speeches and highly selective lectures.

ICRMV received a total of 35 submitted papers this year. This volume contains 21 selected papers, which were presented at the conference. It provides up-to-date, comprehensive and worldwide state-of-the art knowledge in the field of robotics and machine vision. Every paper in this collection underwent rigorous peer-review performed by the conference technical committee and international reviewers before being selected for publication. Studies presented in this volume cover the following five specific topics: computer vision and photography; image analysis and processing; robot design and control; and mechanical control and automation.

We hope that the contents of this volume will prove useful for researchers and practitioners working in the field of robotics and machine vision in their efforts to develop and apply new technologies and processes.

The organizing committee expresses sincere gratitude to all the authors who presented their works at ICRMV 2016 and contributed in this way to the success of this event. Special thanks are due to the authors from abroad for attending the conference and to the reviewers for their great support in improving the quality of the papers in this volume. The organizing committee also addresses warmest thanks to all the members of the international committee for their support and the many others for their contribution in organizing ICRMV 2016.

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